#### **TECHNICAL BROCHURE**

**BSPDDRIVE** 









# Aquavar SPD (Single Pump Drive)

SIMPLEX VARIABLE SPEED PUMP CONTROLLER FOR SUBMERSIBLE AND CENTRIFUGAL PUMPS



## Goulds Water Technology

#### Commercial Water

Goulds Water Technology "Aquavar SPD" variable speed, constant pressure pump controller is designed for the professional pump installer.

With application specific features and Goulds Water Technology designed software, the SPD was developed specifically for use with submersible and centrifugal pumps.

This variable speed controller goes beyond a "standard" drive, giving the pump professional a rugged design that is built for demanding conditions.

#### TYPICAL APPLICATIONS

- Irrigation → Irrigation applications use both submersible and surface pumps. Choose an SPD for control standard 4" and 6" submersible motors as well as turbine pumps and surface centrifugal pumps up to 30 HP.
- Rural Water
- Pressure Boosting
- Agriculture
- **Retrofit** → Existing constant speed control systems
- **Phase Conversion** → 1 phase to 3 phase power
- Two Versions for Submersible and Above Ground Installations

 $SPD_{----}F$  (example: SPD20050F) Models have filters to reduce electrical noise created by drives with long wire runs, typical of submersible installations.

SPP = - - - 0 (example: SPP20050) Models are for above ground installation with short wire runs.

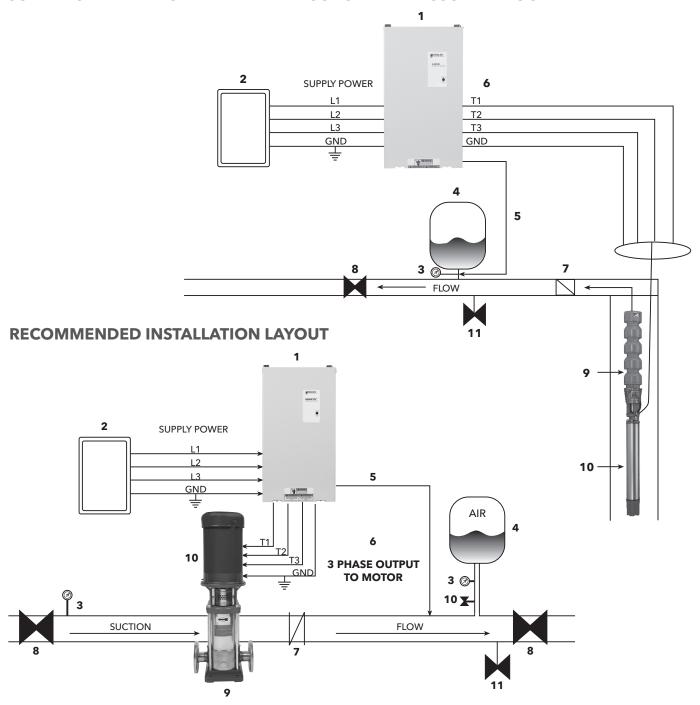


#### **KEY FEATURES AND BENEFITS**

- **Energy Saving** → The SPD is a true variable frequency controller which adjusts motor speed to match the hydraulic needs of the system to maintain pressure. Unlike valve controlled systems, the energy draw is substantially reduced during lower flow while keeping the pump close to its best efficiency. Up to 70% energy savings over fixed speed pumps are common.
- Easy Set-up → Install wiring, set DIP switches and go! Total set up time including wiring is less than 30 minutes.
- NEMA 3R → Outdoor rated enclosure with operating temperatures from -22° F to 122° F!
- Dual Phase Input → UL listed for both three phase and single phase input (de-rated available).
- **Filter** → Includes output filter rated to 1000 feet of motor lead, standard on models with "F" suffix for submersible installations.
- **True Motor Match** → The SPD is designed for the higher amp requirements typical of submersible pumps on start-up. A 10 HP SPD will run a 10 HP submersible pump!
- **Transducer** → As with all Goulds Water Technology drives, the pressure transducer is included.
- Full Diagnostics → Electrical protection and diagnostics, plus a full range of pump protection features such as bound pump or motor shut down, low water or loss of prime shut down.
- **Lockout/Tagout** → Cover can be locked to prevent unauthorized entry.
- Remote on/off → Permits external control by timers (irrigation), float or pressure switches (tank draining) or manual control. Dry contact closure required.
- Hand/Auto Option → Allows the drive to be run at full speed without a pressure transducer for longer periods of time as in the case of new well development or system start up. Turning the control back to auto resumes the automatic pressure tracking and control.
- **Remote Monitoring** → External monitors may be connected to the drive for monitoring pump running speed (4-20 mA output based on speed), pump on, and system fault. The fault indicator can also be connected to devices like an auto-dialer. This enables control of pumps and drives in un-manned locations. The 4-20 mA output can be utilized for functions such as an external dosing system, or chlorine injection.
- **Pressure Drop** → The drive restart value can be adjusted from 5 PSI drop to 20 PSI. This allows for fewer starts and for small leaks that can be common in irrigation systems.
- **Dual Set Point** → Two pressure set points are available, controlled with an external switch, such as a timer.
- No Water Restart → Adjust the time delay after a "dry well" fault, from 10 minutes to 2 hours between each restart. Ideal for low yielding wells.



#### SUBMERSIBLE WELL SPD WITH FILTER CONSTANT PRESSURE LAYOUT



- 1 Aquavar SPD Controller
- 2 Fusible Disconnect
- 3 Pressure Gauge
- **4** Air Diaphragm Tank
- **5** Pressure Transducer
- **6** 3-Phase Output (Always)

- 7 Discharge Check Valve
- **8** Gate Valve (Highly Recommended)
- 9 Pump End
- **10** Submersible Motor (3-Phase)
- **11** Pressure Relief Valve

**NOTE:** For single phase input, connect L1 and L3 terminals, and adjust motor overload switches to 50% of controller rating or lower.

#### **POWER SUPPLY AND WIRING**

#### **Single Phase Power Supply**

The SPD can be used with single phase input power for 208 V or 230 V power supplies. The maximum output of the drive and horsepower must be derated to 50% current.

The chart below shows the full load output current ratings of the controller when single phase or 3 phase power is used. If single phase input power is used the Motor Overload switches must be set to 50% or 40%.

Supply Voltage	Frame Size	Model Number	Nominal HP Rating with 3 Phase Input	Nominal HP Rating with 1 Phase Input	Maximum Output Current with 3 Phase Input	Maximum Output Current with 1 Phase Input
	1	SPD20050	5.0	2.0	17.0	8.1
	1	SPD20050F	5.0	2.0	17.8	8.1
		SPD20075	7.5	2.0	26.4	10.9
	2	SPD20075F	7.5	3.0	26.4	10.9
	2	SPD20100	10.0	5.0	37.0	17.8
		SPD20100F	10.0	5.0	37.0	17.0
208/230		SPD20150	15.0	7.5	47.4	26.4
200/230	3	SPD20150F	15.0	7.5	47.4	20.4
	3	SPD20200	20.0	10.0	60.6	33.0
		SPD20200F	20.0	10.0	00.0	33.0
		SPD20250	25.0	12.0	76.0	40.2
	4	SPD20250F	25.0	12.0	76.0	40.2
	4	SPD20300	30.0	15.0	94.0	47.4
		SPD20300F	30.0	15.0	94.0	47.4
		SPD40050	5.0		8.9	
	1	SPD40050F	5.0		0.9	
	ľ	SPD40075	7.5		13.2	
		SPD40075F	7.5		13.2	
		SPD40100	10.0		18.5	
		SPD40100F	10.0		16.5	
460	2	SPD40150	15.0		23.7	
400		SPD40150F	15.0		23.7	
		SPD40200	20.0		30.3	
		SPD40200F	20.0		30.3	
		SPD40250	25.0		37.5	
	3	SPD40250F	23.0		37.3	
	3	SPD40300	30.0		47.0	
		SPD40300F	30.0		47.0	

#### **STARTING THE SYSTEM**

#### **Setting the Motor Overload Switches**

The Motor Overload Setting Switches adjust the level of motor overload current protection necessary to protect the motor in case of an over current condition.

Bank 1 switches 1, 2 and 3 allow adjustment of the motor overload setting. These switches adjust the motor overload protection as a percentage of the full load output current rating of the controller. Choose a motor overload setting that meets or is less than the motor's SFA rating. For example, if the full load output current rating of the controller is 37A and the motor SFA rating is 33A, the motor overload setting should be set to 85% (33A/37A = 89%, next lowest setting is 85%).

In applications where the pump and motor are not used to the full capacity the system may not draw current close to the motor's SFA rating. In this case choose a motor overload setting that is close to the actual full load running current.

**NOTE:** If single phase input power is used the motor overload switches must be set to 50% or lower or nuisance input phase loss errors can result.

The chart below shows the motor overload setting for each model.

5	WITCH	SETTING	S
BA	NK1	BANK2	BANK3
1 2	3 4 1	2 3 4	1 2
	U = Up	D = Down	
	VERLOAD INGS		/DECEL
BANK1	% OF	BANK1&2	RAMP
1 2 3	RATING	4 1 2	SETTING
UUU	100%	UUU	0.5 SEC
UUD	95%	UUD	1 SEC
UDU	90%	UDU	2 SEC
UDD	85%	UDD	3 SEC
DUU	80%	DUU	4 SEC
DUD	70%	DUD	5 SEC
DDU	50%	DDU	6 SEC
DDD	40%	DDD	7 SEC
	ATER RT TIME	BANK3 1	MIN FREC
BANK2	RESTART	U	30Hz
3 4	TIME	D	15Hz
Ŭ Ü	10 MIN	BANK3	CARRIER
U D	30 MIN	2	FREQ
DU	1 HOUR	U	2KHz
D D	2 HOURS	D	8KHz

					М	otor Over	load Setti	ng		
Supply Voltage	Frame Size	Model Number	100%	95%	90%	85%	80%	70%	50%	40%
	4	SPD20050	47.0	4.4.0	4.4.0	45.4	440	40.5	0.0	7.4
	1	SPD20050F	17.8	16.9	16.0	15.1	14.2	12.5	8.9	7.1
		SPD20075	2/ 4	25.4	22.0	22.4	21.1	10.5	12.2	10 /
	2	SPD20075F	26.4	25.1	23.8	22.4	21.1	18.5	13.2	10.6
	2	SPD20100	27.0	25.2	22.2	24 5	20.7	25.0	10 5	140
		SPD20100F	37.0	35.2	33.3	31.5	29.6	25.9	18.5	14.8
208/230		SPD20150	47.4	45.0	42.7	40.3	37.9	33.2	23.7	19.0
208/230	3	SPD20150F	47.4	45.0	42.7	40.3	37.9	33.2	23.7	19.0
	3	SPD20200	60.6	57.6	54.5	51.5	48.5	42.4	30.3	24.2
		SPD20200F	00.0	37.0	54.5	31.3	46.5	42.4	30.3	24.2
		SPD20250	76.0	72.2	68.4	64.6	60.8	53.2	38.0	30.4
	4	SPD20250F	76.0	12.2	00.4	04.0	00.0	33.2	36.0	30.4
	4	SPD20300	94.0	89.3	84.6	79.9	75.2	65.8	47.0	37.6
		SPD20300F	94.0	07.3	04.0	79.9	75.2	65.6	47.0	37.0
		SPD40050	8.9	8.5	8.0	7.6	7.1	6.2	4.5	3.6
	1	SPD40050F	0.7	0.5	0.0	7.0	7.1	0.2	4.5	3.0
	'	SPD40075	13.2	12.5	11.9	11.2	10.6	9.2	6.6	5.3
		SPD40075F	13.2	12.3	11.7	11.2	10.0	7.2	0.0	5.5
		SPD40100	18.5	17.6	16.7	15.7	14.8	13.0	9.3	7.4
		SPD40100F	10.5	17.0	10.7	13.7	14.0	13.0	7.5	7.4
460	2	SPD40150	23.7	22.5	21.3	20.1	19.0	16.6	11.9	9.5
400		SPD40150F	23.7	22.3	21.3	20.1	17.0	10.0	11.7	7.5
		SPD40200	30.3	28.8	27.3	25.8	24.2	21.2	15.2	12.1
		SPD40200F	30.3	20.0	27.5	23.0	24.2	21.2	13.2	14.1
		SPD40250	37.5	35.6	33.8	31.9	30.0	26.3	18.8	15.0
	3	SPD40250F	37.3	33.0	33.0	31.7	30.0	20.5	10.0	13.0
		SPD40300	47.0	44.7	42.3	40.0	37.6	32.9	23.5	18.8
		SPD40300F	47.0	74./	42.5	40.0	37.0	J2.7	23.3	10.0

#### INPUT AND OUTPUT FUNCTIONS

	CONTROL TE	RMINALS
POSITION	FUNCTION	DESCRIPTION
1	СОМ	SIGNAL COMMON
2	RUN/STOP	CLOSED = RUN OPEN = STOP
3	COM	SIGNAL COMMON
4	HAND/AUTO	CLOSED = HAND OPEN = AUTO
5	СОМ	SIGNAL COMMON
6	INPUT	TRANSDUCER INPUT
7	+24V	24VDC SUPPLY
8	+5V	5VDC SUPPLY
9	COM	SIGNAL COMMON
10	ANALOG OUTPUT	4-20mA OUTPUT
11	SP2/SP1	CLOSED = SETPOINT2 OPEN = SETPOINT1
12	PRESSURE DROP	CLOSED = 20PSI OPEN = 5PSI
13	RELAY1 - NO	MOTOR RUN
14	RELAY1 - NC	STOP: NC = COM
15	RELAY1 - COM	RUN: NO = COM
16	RELAY2 - NO	SYSTEM FAULT
17	RELAY2 - NC	OK: NC = COM
18	RELAY2 - COM	FAULT: NO = COM

The control terminal strips allow for a variety of input and output functions.

**Warning:** Turn off all power to the controller before wiring devices to the control terminals.

**Warning:** Inputs RUN/STOP, HAND/AUTO, SP2/SP1 and PRESSURE DROP are switch inputs. Do not connect power to these inputs or damage to the controller will result. Only connect non-powered switch contacts to these inputs.

**RUN/STOP:** This input allows the pump/motor to be turned on and off by an external switch. Connect the contacts of a non-powered external switch to terminals 1 (COM) and 2 (RUN/STOP). When the switch is closed the controller is in RUN mode (output to motor is enabled). When the switch is open the controller is in STOP mode (output to motor is disabled).

**HAND/AUTO:** This input allows the controller to run the motor at full speed without the use of a pressure transducer. This input can be controlled by an external non-powered switch. Connect the contacts

of a non-powered external switch to terminals 3 (COM) and 4 (HAND/AUTO). When the switch is closed the controller is in HAND mode. While in HAND mode the RUN/STOP input is used to start and stop the motor and the pressure transducer input is ignored. When the switch is open the controller is in AUTO mode. While in AUTO mode the controller uses the pressure transducer feedback to control the speed of the motor.

**INPUT and +24V:** These terminals are the transducer feedback and transducer power supply. Connect the white lead from the transducer cable to terminal 6 (INPUT). Connect the brown lead from the transducer cable to terminal 7 (+24V). Connecting the drain (bare) wire to the chassis allows grounding of the case of the pressure transducer. The controller is configured with a 300 PSI 4-20mA output pressure transducer.

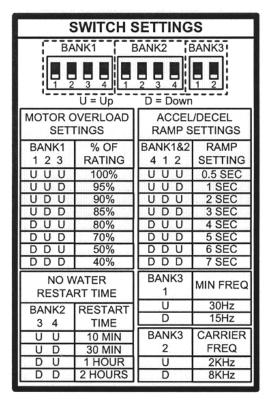
**ANALOG OUTPUT:** This output is a 4-20mA signal based on motor speed (4mA = 0Hz, 20mA = 60Hz) and can be connected to external monitoring or external control devices. Connect terminal 10 (ANALOG OUTPUT) to the 4-20mA input of the external device. Connect terminal 9 (COM) to the negative side of the current loop on the external device. The external device must have an input resistance (impedance) in the range of  $45\Omega$  to  $250\Omega$ . The maximum output voltage is 24V.

**SP2/SP1:** This input allows the system to operate at one of 2 pressure settings. This input can be controlled by an external non-powered switch. Connect the contacts of a non-powered external switch to terminals 5 (COM) and 11 (SP2/SP1). When the switch is closed pressure set point 2 is enabled (preset to 75 PSI when used with a 300 PSI transducer). When the switch is open pressure set point 1 is enabled (preset to 50 PSI when used with a 300 PSI transducer).

**PRESSURE DROP:** This input allows the user to select the amount of pressure drop in the system before the pump starts. This input can be controlled by an external non-powered switch. Connect the contacts of a non-powered external switch to terminals 5 or 9 (COM) and 12 (PRESSURE DROP). When the switch is closed the system pressure will drop 20 PSI (when used with a 300 PSI transducer) before restarting the pump. When the switch is open the system pressure will drop 5 PSI (when used with a 300 PSI transducer) before restarting the pump.

**RUN RELAY:** This output indicates when the pump/motor is running. This output can be used to control power to a light, an alarm or other external device. When the pump/motor is off terminal 13 (RELAY1 - NO) will be open and terminal 14 (RELAY 1 - NC) will be connected to terminal 15 (RELAY1 - COM). When the pump/motor is on terminal 13 (RELAY1 - NO) will be connected to terminal 15 (RELAY1 - COM) and terminal 14 (RELAY 1 - NC) will be open. The relay rating is 250Vac, 5 amps maximum.

**FAULT RELAY:** This output indicates when the system is faulted. This output can be used to control power to a light, an alarm or other external device. When the system is not faulted terminal 16 (RELAY2 - NO) will be open and terminal 17 (RELAY 2 - NC) will be connected to terminal 18 (RELAY2 - COM). When the system is faulted terminal 16 (RELAY2 - NO) will be connected to terminal 18 (RELAY2 - COM) and terminal 17 (RELAY 2 - NC) will be open. The relay rating is 250Vac, 5 amps maximum.



	CONTROL TE	RMINALS
POSITION	FUNCTION	DESCRIPTION
1	СОМ	SIGNAL COMMON
2	RUN/STOP	CLOSED = RUN OPEN = STOP
3	СОМ	SIGNAL COMMON
4	HAND/AUTO	CLOSED = HAND OPEN = AUTO
5	СОМ	SIGNAL COMMON
6	INPUT	TRANSDUCER INPUT
7	+24V	24VDC SUPPLY
8	+5V	5VDC SUPPLY
9	COM	SIGNAL COMMON
10	ANALOG OUTPUT	4-20mA OUTPUT
11	SP2/SP1	CLOSED = SETPOINT2 OPEN = SETPOINT1
12	PRESSURE DROP	CLOSED = 20PSI OPEN = 5PSI
13	RELAY1 - NO	MOTOR RUN
14	RELAY1 - NC	STOP: NC = COM
15	RELAY1 - COM	RUN: NO = COM
16	RELAY2 - NO	SYSTEM FAULT
17	RELAY2 - NC	OK: NC = COM
18	RELAY2 - COM	FAULT: NO = COM

**Digital Input Controls/Relays** 

#### **Motor Overload Setting:**

May be set from 40-100%

#### **Minimum Speed:**

15 Hz and 30 Hz minimum frequency settings. (Permanently set to 30 Hz on filtered product.)

#### **Carrier Frequency:**

2 KHz to 8 KHz (Permanently set to 2 KHz on filtered product.)

#### **Ramp Setting:**

Adjust acceleration and deceleration ramps from .5 to 7 seconds

#### **No Water Restart Time:**

Restart delay after ddry well or loss of prime fault adjustable from 10 minutes to 2 hours.

## Goulds Water Technology

#### Commercial Water

Carrier (IGBT switching) frequency: 2 KHz to 8 KHz

**Outputs** Analog output: 4-20mA output based on drive frequency. 0-60 Hz.

Pump run status: Relay to indicate pump run status.

Drive fault status: Relay to indicate pump, motor or controller fault. May be connected to

outside warning device or auto-dialer.

LED Lights: Green - standby or pump running

Orange - Under voltage

**Red** - Number of blinks determine: replace controller, no water/loss of prime, sensor fault, pump or motor bound, short circuit/ground fault, input phase loss, temperature, over-voltage, or motor overload.

**Electrical Efficiency** Over 95% at Full Load

No water restart time Adjustable restart time for "dry well" function from 10 min. to 2 hours.

**Protection Against** Short circuit, under voltage, motor overload, temperature, dead heading, run out, suction

loss, sensor fault, bound pump, overvoltage, static discharge, dry well.

Max. Elevation 2000 m (6600 ft.) -22° F to 122° F **Ambient Temp.** 

Max. Humidity 95% at 104F non-condensing

**Air Pollution** Avoid mounting in areas with excessive dust, acids, corrosives and salts.

UL, cUL, CE **Approvals** 

**Enclosure** Painted Steel enclosure, NEMA 3R, IP43, (rain tight)

Wall mount Mounting

Attached heat sink and fan. Cooling

4-20 mA rated to 300 PSI with 180-inch, 3 core shielded cable, with internal case ground. **Transducer** 

Integrated filters protect the motor from voltage spikes even with up to 1,000 feet of wire between controller and motor.

(Optional)

#### **WEIGHTS AND DIMENSIONS**

**Output Filter** 

	Filtered Product	<b>Non-Filtered Product</b>		
Size 1	21 lbs.	17 lbs.		
Size 2	27 lbs.	22 lbs.		
Size 3	52 lbs.	41 lbs.	SIZE 3	SIZE 4
Size 4	110 lbs.	84 lbs.	12,66	12,68
	SIZE 1 8,92 1904 of aloth of a	21,72 (Hole to Hole) 21,72 (Hole to Hole) 22,79 21,73 22,47	32.24 (Hole to Hole) 09'E! 6.03 31.57 32.75	22.24 (Hole to Hole)  7.61  7.61  7.61  33.77

#### **TROUBLESHOOTING**

#### General

The Aquavar SPD drives are self-diagnosing controllers. If a problem occurs, observe the Status Code Indicator Light on the front of the unit. No Status Code Indicator Light means either no or low input voltage (less than 140Vac).

Refer to the status code label on the side of the controller access cover to diagnose system errors. See the following diagram.

5	STATUS CODES
	GREEN LIGHT CODES
CONSTANT	STANDBY
BLINKING	PUMP RUNNING
(	DRANGE LIGHT CODES
CONSTANT	UNDER VOLTAGE
	RED LIGHT CODES
CONSTANT	REPLACE CONTROLLER
2 BLINKS	NO WATER/LOSS OF PRIME
3 BLINKS	SENSOR FAULT
4 BLINKS	PUMP OR MOTOR BOUND
5 BLINKS	SHORT CIRCUIT/GROUND FAULT
6 BLINKS	INPUT PHASE LOSS
7 BLINKS	TEMPERATURE
8 BLINKS	OVER VOLTAGE
9 BLINKS	MOTOR OVERLOAD

Red Flashes	Fault Code	Restart Action
Constant	Replace Controller	Controller will not restart. Power must be reset to clear the fault.
2 Blinks	No Water/Loss of Prime	Controller will restart automatically according to the No Water Restart Time switches (switches 3 & 4 of bank 2).
3 Blinks	Sensor Fault	Controller will restart automatically when the sensor signal is within the valid operating range.
4 Blinks	Pump or Motor Bound	Controller will restart automatically 5 times. After 5 faults the power must be reset to clear the fault.
5 Blinks	Short Circuit/Ground Fault	Controller will not restart. Power must be reset to clear the fault.
6 Blinks	Input Phase Loss	Controller will restart automatically 5 times. After 5 faults the power must be reset to clear the fault.
7 Blinks	Temperature	Controller will restart automatically when temperature is within the operating range of the controller.
8 Blinks	Over Voltage	Controller will restart automatically when the input voltage is within the operating range of the controller.
9 Blinks	Motor Overload	Controller will restart automatically.

## Goulds Water Technology

#### **VFD INPUT WIRE SIZING CHARTS**

Mathematical Model	Morey   More									Σ	aximu	m Allo	wable	Condu	ictor L	ength	(40°C	Ambie	int, 5%	Maximum Allowable Conductor Length (40°C Ambient, 5% Voltage Drop)	e Drop				
Action                  Action                 Action                 Action                 Action                  Action                  Action                  Action                  Action                          Action                         Action                       Act	Part   14   15   16   16   16   16   16   16   17   18   18   18   18   18   18   18			Rating	S								J	onduc	tor Siz	e (75°	C Rate	d Wire	(£	•			-	-	
1,	1. 4. 6. 10. 10. 10. 10. 10. 10. 10. 10. 10. 10	ontroller	Motor HP	Motor	Input	4	12	10		9	4	ო	8												1000
1	1.   1.   1.   1.   1.   1.   1.   1.		1/2	2.9	7.2	400	618	1020	È	2348	3530	4242	$\vdash$	$\vdash$		H	$\vdash$	-	$\vdash$	H		$\vdash$	H	$\vdash$	22421
1   4   5   5   5   5   5   5   5   5   5	1,    1,		3/4	3.8	9.4	301	467	775	$\vdash$	1790	2693	3236		_		$\vdash$	$\vdash$	_		_	_	_	Н		17111
1.   1.   1.   1.   1.   1.   1.   1.	1. 1 19.		1	4.7	11.6	239	374	623		1445	2175	2615					_							_	13834
1   1   1   1   1   1   1   1   1   1	8. 8. 6. 7. 8. 7. 8. 7. 8. 8. 128	2307	11/2	6.1	15.1	178	282	475		1110	1673	2012												9784	10659
1   1   1   1   1   1   1   1   1   1	5.0   1.   1.   1.   1.   1.   1.   1.	Sinale	2	7.6	18.8		219	375		887	1340	1612												7852	8555
1.   1.   1.   1.   1.   1.   1.   1.	2.1   2.1	Phase	3	10.1	25.0			273		662	1003	1209				$\vdash$		H	H						6437
1.   1.   1.   1.   1.   1.   1.   1.	4.3   4.4   4.4   4.4   5.4   4.4   5.3   6.0   6.6   6.6   6.5   6.7   1.5   6.0   6.6   6.5	Input	5	17.0	42.1					378	583	708					$\vdash$								3824
10   10   10   10   10   10   10   10	1.2 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.		71/2	26.0	64.3						366	449	573												2499
4.   4.   4.   4.   4.   4.   4.   4.	1.4   1.		10	33.0	81.7								144		$\vdash$	$\vdash$	$\vdash$		H					1806	1968
4.6                 2.9                 3.4                 8.6                 1.0                 9.0                1.0                1.0                 1.0                 1.0                 1.0                 1.0                 1.0                 1.0                 1.0                   1.0                 1.0                 1.0	1.4		15	47.4	117.3																			1256	1369
	1.   1.   1.   1.   1.   1.   1.   1.		1/2	2.9	3.4	818	1263	2087		4908	7511	9123		-		-		-		-					63177
14 4 7 5 5 5 6 6 7 7 7 8 7 8 7 8 7 8 7 8 7 8 7 8 7 8	1.5 38.0 776 78.6 78.8 78.9 78.0 78.0 78.0 78.0 78.0 78.0 78.0 78.0		3/4	3.8	4.5	623	962	1591		3745	5731	6962	-		-	<u> </u>		-	-	-		_	$\vdash$		48214
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,	1.   1.   1.   1.   1.   1.   1.   1.		1	4.7	5.5	501	776	1285		3027	4633	5628													38981
2                 3                4                7                7                4                4                7                6                9                9                4                4                7                4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                 4                4                 4                 4                 4                 4                 4                 4                 4                  4                 4                 4                 4	1.9 3.04 4.74 790 1403 1212 2615 3342 4444 5404 6530 771 728 1210 1210 11075 1125 1125 1125 1125 1125 1125 1125 11		11/2	6.1	7.2	383	595	886		2331	3568	4335	_	$\vdash$	_		-	_	_	_	_		-	_	30035
3                 10                 11                 24                35                 90                 405                 265                 405                 670                 405                 670                 405                 670                 400                 400                 400                 400                 400                 400                 400                 400                 400                 400                 400                 400                     400                 400                 400                 400                 400                 400                 400                 400                 400                 400                 400                 400                  400                     400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                      400                  400                  400                  400                  400                  400                  400                  400                  400	1.9		2	7.6	8.9	304	474	790		1869	2863	3478	_	_				_	_	$\vdash$			_		24107
5         170         200         186         339         620         370         280         4136         4136         4136         4136         4136         4136         6137         6139         6139         6139         6130         6117         6143         6140	0.0 0 196 339 527 528 1730 1548 1970 2416 2915 3319 4128 4139 545 6654 6727 2720 2740 2750 2750 2750 2750 2750 2750 2750 275	2307	က	10.1	11.9	224	351	590		1403	2152	2615					-			-					18140
716         2.60         30.6         3.3         5.0         4.0         1.0 </td <td>9.8 9. 9. 9. 9. 9. 9. 9. 9. 9. 9. 9. 1005 1289 1570 1790 2206 2700 3107 3565 9599 432, 9420 5704 570 5704 970 970 970 970 970 970 970 970 970 970</td> <td>Phase  </td> <td>5</td> <td>17.0</td> <td>20.0</td> <td></td> <td>1%</td> <td>339</td> <td></td> <td>826</td> <td>1272</td> <td>1548</td> <td></td> <td></td> <td></td> <td></td> <td>_</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>10777</td>	9.8 9. 9. 9. 9. 9. 9. 9. 9. 9. 9. 9. 1005 1289 1570 1790 2206 2700 3107 3565 9599 432, 9420 5704 570 5704 970 970 970 970 970 970 970 970 970 970	Phase	5	17.0	20.0		1%	339		826	1272	1548					_								10777
1.   1.   1.   1.   1.   1.   1.   1.	8.8	Input	3/17	26.0	30.6				333	530	823	1005	H	Н		H	$\vdash$	H	H		H		H	6319	7045
15   16.0   10	4.1		10	33.0	38.8				254	409	641	785												4978	5550
20         60.0         70.6         7	0.6 5.9 6.8 6.9 6.0 6.0 6.0 6.0 6.0 6.0 6.0 6.0 6.0 6.0		15	46.0	54.1					280	447	553	713	-		-	-	-	-	-	-	-	-	3570	3980
25         76.0         89.4         1         410         509         624         734         966         1069         1073         1420         167         186         167         167         147         1480         167         168         169         169         168         169         168         169         168         169         168         169         168         169         168         169         169         169         169         169<	9.4   9.6   1.6		20	0.09	70.6							412	536	$\dashv$	_	$\dashv$	$\dashv$	_	-	_	_	_	$\dashv$	2735	3050
30         94.0         110.6         98         94.3         54.4         49.3         56.4         72.0         86.5         96.9         100         110.6         110.7	0.0 Sign sign sign sign sign sign sign sign s		25	76.0	89.4								410						-					2158	2406
5         8.5         10.0         339         843         1409         2145         3339         5117         6219         745         1637         16351         16321	2.5 336 643 1409 1415 339 5117 6219 7945 9462 11677 1353 1459 1429 12894 12894 12899 32461 3894 3804 3804 3804 3804 350 5.3 335 534 643 337 4059 5189 6312 753 6894 10821 12697 14274 15846 17457 18899 21224 22913 25278 2599 25.3 3894 3404 3404 12483 1375 14892 1174 3184 12483 1375 14892 1174 1248 12483 1375 14892 1172 1438 1375 4418 1374 1248 1375 14892 1375 14892 14284 12484 12483 1375 14892 14284 12484		30	94.0	110.6										$\dashv$	$\dashv$	$\dashv$		$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	1943
7½         13.0         15.3         335         534         906         1397         1724         1280         1280         1724         1280         1480         1724         1280         1480         1724         1280         1480         1724         1280         1880         1724         1280         1724         1280         1880         1724         1280         1880         1724         1880         1724         1880	5.3         385         534         906         1391         2174         337         4059         5189         6312         6302         6907         6807         10201         11249         14284         1489         11324         1289         1480         2172         2013         337         406         670         6807         1600         11244         1289         1785         1892         18		5	8.5	10.0	539	843	1409	$\dashv$	3339	5117	6219	$\dashv$		$\dashv$	$\rightarrow$	_	_	-	-	$\dashv$	$\dashv$	$\dashv$	_	43109
10         16.5         19.4         406         701         1087         1704         662         498         606         6967         682         1001         11244         12483         1372         1489         1067         491         6108         7170         8062         9852         9851         1671         1894         1895         1994         1895         1895         1896         1896         1895         1896 </td <td>7.1         406         701         1087         4704         2622         3192         4908         6006         6967         8522         10001         11244         12483         13752         14882         1671         1805         19916         1992         1992         1992         1992         1992         1992         1993         <t< td=""><td></td><td>71/2</td><td>13.0</td><td>15.3</td><td>335</td><td>534</td><td>906</td><td></td><td>2174</td><td>3337</td><td>4029</td><td><math>\dashv</math></td><td><math>\dashv</math></td><td>-</td><td><math>\dashv</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td>-</td><td><math>\rightarrow</math></td><td>-</td><td>-</td><td>28186</td></t<></td>	7.1         406         701         1087         4704         2622         3192         4908         6006         6967         8522         10001         11244         12483         13752         14882         1671         1805         19916         1992         1992         1992         1992         1992         1992         1993 <t< td=""><td></td><td>71/2</td><td>13.0</td><td>15.3</td><td>335</td><td>534</td><td>906</td><td></td><td>2174</td><td>3337</td><td>4029</td><td><math>\dashv</math></td><td><math>\dashv</math></td><td>-</td><td><math>\dashv</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td><math>\rightarrow</math></td><td>-</td><td><math>\rightarrow</math></td><td>-</td><td>-</td><td>28186</td></t<>		71/2	13.0	15.3	335	534	906		2174	3337	4029	$\dashv$	$\dashv$	-	$\dashv$	$\rightarrow$	$\rightarrow$	$\rightarrow$	$\rightarrow$	-	$\rightarrow$	-	-	28186
15         23.0         27.1         482         763         1786         3554         4301         4991         4100         4100         4101         410	7.1 482   482   763   1207   1808   2279   2918   3554   4301   4991   6108   7170   8062   8952   8963   10674   11994   12949   14286   5.33   3819   4676   5491   6176   6859   7558   8180   9193   9925   10951   9355   935		10	16.5	19.4		406	701	$\dashv$	1704	2622	3192	$\dashv$	$\dashv$	-	$\dashv$	$\dashv$	$\dashv$	$\rightarrow$	$\rightarrow$	$\dashv$	$\dashv$	$\dashv$	-	22206
20         35.3         35.8         909         1418         1734         225         2715         3288         3819         4676         5491         6176         6859         7558         8180         9193         992         1091         3054         3784         4446         5003         5557         6124         660         752         8045         8180         9787         1079         2170         2421         2869         3784         4446         5003         5557         6124         660         752         8045         8878         8878         8878         8878         3787         4446         5003         5557         6124         660         755         8878         8878         8878         1789         2072         2421         2869         3784         4446         5003         5557         6124         6103         8787         4879         8787	5.3 S.5 S.5 S.5 S.5 S.5 S.5 S.5 S.6 S.5		15	23.0	27.1			482	$\dashv$	1207	1868	2279	_	$\dashv$	$\dashv$	$\dashv$	$\dashv$		-		$\dashv$	-	$\dashv$	-	15930
25         37.0         43.5         9.0         37.0         48.6         50.0         55.3         61.4         66.0         55.3         61.4         66.0         55.3         61.4         66.0         55.3         61.0         66.0         70.0         40	3.5		20	30.0	35.3				268	606	1418	1734	$\dashv$	$\dashv$		$\dashv$	-	$\dashv$	-					10951	12211
30         47.0         55.3         6.0         70.6         87.4         1080         1395         1709         2077         2421         2969         3492         3922         4364         4365         55.3         583         639         698           40         60         70.6	5.3   8.6   1.08   1.08   1.09   1.09   1.00		25	37.0	43.5					721	1135	1394	$\dashv$	$\dashv$	-	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	-	$\dashv$	8878	0066
40         60         70.6         70.6         824         1072         1320         1610         1882         2331         2725         3071         3414         3766         4079         4586         4954         5470         4970           50         79         92.9         79         105.9         78         1785         204         1783         2026         2259         2495         2707         3049         3757         4151           75         109         105.9         10         105.9         10         10         128.2         2049         1230         1464         1660         1852         2049         2256         2049         22	2.9 S.	460V,	30	47.0	55.3						874	1080	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$		$\dashv$	$\dashv$	$\dashv$	2869	7791
50         79         92.9         78         976         1198         1409         1738         2054         2320         2581         2850         3479         3757         4151           60         90         105.9         105.9         105.9         105.9         105.9         228         2495         220         2495         270         3049         3293         3641           100         145         170.6         109         1230         1464         1660         1852         2049         220         250         220<	2.9       785       976       1198       1409       1738       2054       2320       2581       2850       3409       3479       3479       3479       3479       3479       3479       3479       4151         15.9       15.9       10.6       10.6       10.2       10.4       10.6       182       2049       2226       2511       2712       3001         10.6       10.6       10.6       10.7       1	Phase	40	09	70.6							824	$\dashv$	$\dashv$	_	$\dashv$	$\dashv$	-					-	5470	6100
90         105.9         105.9         105.9         841         1036         1235         1543         2028         2259         2455         2707         3049         3293         3641           109         128.2         170.6         128.2         2049         1230         1660         182         2049         2226         2511         2712         3001           145         170.6         170.6         170.6         170.7         1224         1371         1521         1658         1875         2027         2248           180         211.8         180         120         124         1072         1224         1371         1651         1658         1875         2027         2248           220         258.8         180         120         1249         1621         1803         1871         1803           270         317.6         317.6         317.6         317.6         317.2         182         1862         1862         187         1862         187         1862         1862         1862         1862         1862         1862         1862         1862         1862         1862         1862         1862         1862         1862	15.9   841   1036   1225   1514   1793   2028   2259   2495   2707   3049   3293   3441   18.2   18.	Input	50	79	92.9								$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$	$\dashv$		$\dashv$	4151	4629
109         128.2         128.2         128.2         224         127.2         221         27.2         27.1         27.2         301           145         170.6         170.6         170.6         170.6         170.6         170.6         170.6         170.6         170.6         170.7	18.2       18.2       18.2       18.2       18.2       2049       2226       2511       2712       3001         30.0       10.0		09	06	105.9									$\dashv$	-	$\dashv$	$\dashv$	$\dashv$	$\dashv$		$\dashv$			3641	4061
145         170.6         100.2         170.6         100.2         1224         137         152         168         187         2027         2248           220         258.8         100.2	0.0.6       10.2       10.2       12.2       15.21       15.21       16.51       18.5       20.7       2248         1.8       1.8       1.0 <td></td> <td>75</td> <td>109</td> <td>128.2</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>J .</td> <td>-</td> <td><math>\dashv</math></td> <td>_</td> <td>-</td> <td></td> <td></td> <td>-</td> <td><math>\dashv</math></td> <td>3001</td> <td>3348</td>		75	109	128.2										J .	-	$\dashv$	_	-			-	$\dashv$	3001	3348
180     211.8     1083     120     1320     1499     1621     1803       220     258.8     101     1063     1212     1312     1466       270     317.6     1063     1063     107     1063     1182     1182	1.8       108.3       107.1       1320       1499       1621       1803         18.8       18.8       108.3       1212       1312       1466         7.6       100.3       100.3       1212       1312       1466         100.3       100.3       100.3       182       1182         100.3       100.3       100.3       1182       1182		100	145	170.6												-	_	_	$\dashv$	$\dashv$	$\dashv$	$\dashv$	2248	2509
220     258.8       270     317.6	18.8     1063     1212     1312     1466       7.6     1063     1212     1312     1465       1063     1212     1182     1182       1182     1182     1182		125	180	211.8														7	$\dashv$	$\dashv$	$\dashv$	$\dashv$	1803	2013
270         317.6         1052         1182	7.6		150	220	258.8																106				1638
	Input connections f		200	270	317.6																		1052		1323

Lengths in BOLD require 90°C wire Input connections for models SPD2030 For output cable sizing and maximum length, consult MAID Manual (BMAID).

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